Principles and methods of calculating hybrid contactors of direct current, controlled by an electric drive current

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Abstract - It has been shown that the principle of controlling the current of an electromagnetic drive of a hybrid contactor of direct current is realized by introducing a special control electric circuit in parallel with a drive coil by means of turning on a power SK (semiconductor key), which contains a condenser, setting the time and controlled low-power transistor key, in an output circuit of which a low-power optron thyristor is included, moreover, an auxiliary transistor key, providing the current discharge with the help of additional secondary electric winding when commutation current flows from the circuit of the main contactors to the circuit of a power semiconductor key, is turned on in parallel to the mentioned condenser.

The peculiarities of the processes of charging and discharging of a condenser, which sets the time, in different operating conditions of a contactor, have been determined. Whereby, it has been found out that for providing reliable circuits commutation it is necessary that a condenser charging time, setting the time up to the level of voltage, providing turn-on of a low-powered optron thyristor when a contactor is turned on, shouldn’t exceed the value of minimum time of its turn-on and the time of the condenser discharge when turned off shouldn’t be lower than the minimum time of a contactor turn-off. It allows to determine the parameters of the elements, providing reliable commutation of a contactor.

As a result of the research it has been shown that the proposed hybrid contactors due to the introduction of electromagnetic drive current control and new connections as compared with the existing ones, possess the properties increasing their competitiveness. They also have increased operation reliability, reduced dimensions and cost, their production and technological indices are improved and the sphere of their application is broadened.

The possibility of creating competitive reliable hybrid contactors of direct current on the currents 100-630 A and voltage up to 1000 V, which function in hard maintenance conditions, is considered to be an applied aspect of putting into practice the research results obtained.

Key words – hybrid contactor, direct current, main contacts, power semiconductor key, current control, electromagnetic drive.

I. INTRODUCTION. URGENCY OF THE RESEARCH AND TARGET SETTING

Hybrid contactors of direct current or contactors with arcless commutation combine positive qualities both of contact apparatuses (small loses of power in on position), and non-contact ones (arcless current commutation). In these contactors parallel to the main contactors of the base contactor, as a rule, with electromagnetic drive, completely controlled power semiconductor key (SK) is connected, providing arcless commutation of disconnecting contacts. Its turn-on and turn-off is made the control circuit. In on position of a contactor a completely controlled SK is bypassed by the main contacts. So, SK is under the load just for a short period of time (some ms) at loading commutation allowing to use completely controlled power semiconductor devices (PSD) (IGBT-transistors: GTO- thyristors etc) without coolers using natural cooling when constructing SK. Besides, the use of a blowout system of the base contactor is not necessary. It is very important for contactors intended for the net voltage of higher than 500 V, when the commutation process of inductance loading becomes complicated.

As a result, commutation wear resistance of hybrid contactors increases dozens of times and approaches the mechanic one when an apparatus mass is a bit increased (up to 20-30%). However, in the case of using expensive completely controlled power SK in these contactors, their price is two times or [1] or higher than of common classical contactors.

That is why, from the technical and economic point of view, they should be used in hard maintenance conditions, characterized by frequent commutations of active and inductance loading and in conditions of increased explosion and fire safety requirements.

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Nowadays, the sphere of using hybrid commutation apparatuses (including contactors) of direct current widened greatly due to the development of direct current nets, in which renewable sources of electric power are used (solar and wind power stations) [3, 4].

In connection with that the works, aimed at the development of new principles of creating hybrid commutation apparatuses and methods of their calculation, providing the increase of their competitiveness at the world market of electro-technical products, are urgent and in demand. The review of scientific works for a period of 10 years is given by the authors in [5] and shows that such research work is carried out worldwide [6-8].

II. THE AIM AND THE TASKS OF THE RESEARCH

The aim of the research is to develop the principles and methods of calculating operating conditions and parameters of hybrid contactors of direct current (with an electromagnetic drive), controlled by the electric drive current.

The following tasks are to be solved:
- To prove that the principle of controlling a hybrid contactor by the current of its electromagnetic drive allows to increase its competitiveness as compared with the existing ones;
- To study nonstationary electromagnetic processes, providing electromagnetic drive current control by a contactor;
- To elaborate the methods of calculating electronic circuit elements, providing electromagnetic drive current control and to give recommendations on the choice of their parameters and operating conditions.

III. TECHNICAL SOLUTIONS ON CREATING HYBRID CONTACTORS OF DIRECT CURRENT AND THEIR ANALYSIS

Technical solutions in the form of an electric circuit of a two-pin hybrid contactor of direct current, controlled by the current of its electromagnetic drive, have been worked out at O.M. Beketov National University of urban economy in Kharkiv (Ukraine, Kharkiv). This principle is realized in such a way that a special electronic circuit of control with a condenser, setting the time, and a controlled transistor key with an optron thyristor connected with its input circuit, is introduced in series with the coil of electromagnetic drive. This circuit provides reliable contactless turn-on and turn-off of a completely controlled SK, as the main contactor contact is by-passed when the loading is commutated by an apparatus. The main technical solutions, applied in the contactor, are protected by patent [9, 10].

An electric circuit of the given contactor is presented in figure 1.

A classical double-pole contactor with an electromagnetic drive is applied as the base contact apparatus.

Such elements of a contactor as the main contacts MC1 and MC2, IGBT-transistor VT3 with a reverse diode VD7, primary coils W1.1, W1.2 of a current transformer TA1 form the main circuit of a contactor on the circuit. At the same time the contacts 1 and 2 MC1 and MC2 are adjusted in such a way that the second contact is broken later than the first one (time latency is 8-9 ms), and instead of IGBT-transistor a dual-operation thyristor can be applied.

A thyristor block Rₐ is intended for spilling the power accumulating in a circuit inductance, and an optron thyristor VS₃ – for spilling the power accumulated in a loading inductance. The latter element allows to use the proposed contactor in non-reverse circuits. The rest elements form the circuit of controlling the commutation of the main contacts or VT₃.

Such elements as the button START and STOP, auxiliary contacts MK₁.1 and the coil of electromagnet MK₁ provide a drive control and thus the commutation of the main contacts.

Such elements as a diode bridge (VD1 – VD4), a condenser C₁, setting the time, a transistor VT₂, optron thyristor VS₁, resistors Rₐ – Rₐ, a condenser C₃, a voltage regulator VD₆ and a bilateral voltage selector VD₈ provide turn-on of a transistor VT₇ (or a dual-operation thyristor). In their turn, such elements as a transistor VT₁, resistors R₄ – R₄, a diode VD₅, secondary coils W₂.1 and W₂.2, diodes VD₉ and VD₁₀, a commutating condenser C₅, a commutating thyristor VS₂, resistors R₉ and R₉, an input circuit of an optron thyristor VS₃ provide turn-off VT₃ (or a dual-operation thyristor).

While a contactor is powered off all elements of its electronic circuit are de-energized and in on-position just a small amount of elements, included into the circuit of an electromagnetic drive, are under load.

A detailed description of a contactor work is presented in [9, 10].

As can be seen from the analysis presented in [5, 9, 10], the technical solutions proposed by the authors allow to create hybrid contactors, providing reliable arcless commutation both in on-position and when powered off. They don’t need the use of costly large standard driver with a special power unit as well as an additional source of power. Furthermore, as compared with the existing contactors, they possess the following additional positive characteristics:

1) Increased operation reliability, provided by the following factors: excluding of a less-than-perfect contact circuit, created on the basis of a current relay, from the controlling circuit of a power SK, complete excluding of a possibility of an emergency restart of a power SK upon power failure, and economical operating conditions of the elements of a contactor electronic circuit as well as excluding of a voltage influence on the elements of a controlling circuit;

2) Reduced dimensions, mass and cost due to considerable simplification of a controlling circuit (excluding of the time relay and a large non-process current relay, simplification of the connections between the electric contacts);

3) The parameters and operating conditions of the circuit controlling an electrical part don’t depend on the net voltage and are determined only by the turned off current, it allows to use the proposed technical solutions also for creating hybrid contactors for the voltage higher than 1000 V;
4) The absence of the commutation zone with an arc increases its commutation durability as well as allows to apply it in conditions of strict explosion and fire safety requirements.

![Diagram of a hybrid double-pole electromagnetic contactor](https://example.com/diagram.png)

**Fig. 1.** Hybrid double-pole electromagnetic contactor of direct current controlled by an electric drive current

The properties mentioned above essentially increase the competitiveness of the proposed contactor due to the increase of the maintenance properties and production simplification.

For substantiation of the results obtained and for providing practical realization it is necessary to study the processes which haven’t been considered before, but occurring in a contactor circuits in case of loading commutation. On the basis of the data obtained the necessary calculation techniques are expected to be worked out.

**IV. THEORETIC RESEARCHES OF NONSTATIONARY PROCESSES IN THE CIRCUITS OF HYBRID CONTACTORS**

The data of the researched processes are presented below. The main processes occur in the circuit of electromagnetic drive of a contactor in case of its commutation. The design circuit for studying these processes is presented in figure 2.

The following symbols are used in the circuit:
- $R_k$ - active resistance of a drive coil;
- $L_k$ - inductive resistance;
- $C_1$ - condenser connected with a coil in series;
- $R_b$ - regulated resistor, connected with the input circuit of the optron thyristor;
- $VT2$ – transistor key;
As the resistor resistance $R_e$ is enormously higher than that of the resistor $R_k$ (in modern low power transistors the coefficient of the current transmission $β > 100$), it is possible to consider with a fractional error that the equivalent value of resistance, connected in parallel to the condenser $C_1$, will be the following: $R_e = R_k$.

The process of charging a condenser $C_1$ in case of a turned on contactor is divided into two stages. The first stage lasts up to the moment of turning on a transistor key $VT2$, i.e. up to the voltage reaches the voltage value of the breakdown of the regulator $VD1$. In this case a transmission process in the circuit is determined with the following equation:

$$u_k = i_k \cdot R_k + L_k \cdot \frac{di_k}{dt} + u_c$$

(1)

After the corresponding transformations we have:

$$\frac{du_c}{dt} + \frac{R_k}{L_k} \frac{du_c}{dt} + u_c \cdot \frac{1}{L_k C_1} = \frac{u_k}{L_k C_1}$$

(2)

According to [11] its solution looks like that:

$$u_c = U_K + \frac{u_k}{p_2 - p_1} \cdot \left( e^{p_1 t} - p_1 \cdot e^{p_2 t} \right),$$

(3)

$$i_k = \frac{u_k}{L_k (p_1 - p_2)} \cdot \left( e^{p_1 t} - e^{p_2 t} \right)$$

(4)

where $p_2 = \frac{R_k}{2L_k} + \left( \frac{R_k}{L_k} \right)^2 \cdot \frac{1}{L_k C_1}$

In this case it is supposed that a charging process is aperiodic, i.e. $\left( \frac{R_k}{L_k} \right)^2 \cdot \frac{1}{L_k C_1} > 0$

The second stage starts from the moment of turning on a transistor key $VT2$ in case of a regulator breakdown $VD1$. In such case ($R_e = R_0$):

$$U_c(0) = U_{CT}, I_c(0) = \frac{U_{CT}}{R_E} \geq I_{\text{turn-on vs1}}$$

(5)

where $U_{CT}$ - the voltage of the regulator breakdown $VD1$.

$R_E = R_0$, $I_{\text{turn-on vs1}}$ - turning on current of optron thyristor VS1 (fig. 1). For determining the time of a transistor key closing ($t_1$) it is necessary to solve the following transcendental equation:

$$U_{CT} = U_k + \frac{u_k}{p_1 - p_2} \cdot \left( e^{p_1 t} - p_1 \cdot e^{p_2 t} \right)$$

(6)

In case when $p_1 \leq p_2$ it is possible to use the following equation for this circuit:

$$t_1 = \frac{\ln \left( U_{CT} - U_k \right) - \ln \left( -U_k \cdot p_2 \right)}{p_1 - p_2}$$

(7)

For normal operation of an electronic circuit of control it is necessary that

$$t_1 \geq t_{\text{turn-on min}} = 0.75 t_{\text{turn-on}}$$

The equation of a transmission process at the second stage looks as follows:

$$u_k = i_k \cdot R_k + L_k \cdot \frac{di_k}{dt} + u_c$$

(8)

where $i_k = C_1 \cdot \frac{du_c}{dt} + \frac{u_c}{R_k}$

Or after the corresponding transformations:

$$\frac{du_c}{dt} + \frac{R_k}{L_k} \frac{du_c}{dt} + u_c \cdot \frac{1}{L_k C_1} = \frac{u_k}{L_k (p_1 - p_2)} \cdot \left( e^{p_1 t} - e^{p_2 t} \right)$$

(9)

Using known calculation techniques of transmission processes of electric circuits [11], we obtain:

$$u_c = U_k \cdot k - A \cdot e^{p_1 t} + \left( A + U_{CT} - U_k \cdot k \right) \cdot e^{p_2 t}$$

(10)

where $A = \frac{1}{p_1 - p_2} \left[ \left( U_{CT} - U_k \cdot k \right) + \frac{I_c(0)}{C_1} \right]$

$$k = \frac{R_k}{R_k + R_E}$$

$$p_1' = A \pm \sqrt{A^2 - \frac{1}{\kappa L_k C_1}}$$

$$p_2' = \frac{1}{2} \cdot \left( \frac{R_k}{L_k} \right)^2 \cdot \frac{1}{R_k C_1}$$

So, in a stable condition the voltage on the condenser $C_1$ is equal to $U_k \cdot k = U_0$.

Practically the time of a condenser charge is determined from the equation (10) assuming that $U_k \cdot k = U_0$. However, if $p_2' \gg p_1'$, this time can be determined from the equation:

$$t_2 = \frac{\ln \left( \frac{A}{0.05 \cdot U_k} \right) - \ln 0.95 \cdot U_0 - \ln A}{p_1'}$$

(11)
In this case the full time of a condenser charge will be
\[ t_{\text{charge}} = t_1 + t_2. \]

When a contactor is turned off, a condenser \( C_1 \) starts discharging through an open semiconductor key \( VT2 \) and a resistor \( R_0 \), and it finishes when the voltage on the condenser occurs and it is equal to the voltage of a regulator breakdown \( VD1 \).

The equation of a transmission process in this case looks like that:
\[ R_E \cdot C_1 \frac{du_c}{dt} + u_c = 0 \quad (12) \]

When \( t = 0 - U_0 = U_K \cdot k \). Then
\[ u_c = U_K \cdot k \cdot e^{-t/t}, \quad (13) \]

where \( \tau = R_E \cdot C_1 \).

The time of a condenser discharge \( (t_{\text{disch}}) \), until the voltage is \( U_{\text{CTR}} \), will be determined from the following equation:
\[ t_{\text{disch}} = \tau \cdot \ln \frac{U_K - k}{U_{\text{CTR}}} \quad (14) \]

For the normal operation of a circuit controlled by a contactor it is necessary that the following in-equation to be carried out:
\[ t_{\text{disch}} \leq t_{\text{turn-off-max}} = 1.25 \cdot t_{\text{on-off}} \quad (15) \]

For reducing over-voltage by the current of an input circuit of optron thyristor \( VS1 \) it is recommended to fulfil a stipulation \( U_K - k \leq (2 \pm 3) \) in this case the stipulation will be fulfilled at which a condenser discharge \( C_1 \) with the help of a transistor key \( VT1 \) (fig. 1) will occur only in case of full transmission of current to the by-passing SK, i.e. the conditions, at which a reliable arcell commutation of a circuit at a contactor cutoff will be provided.

For reducing the influence of a condenser, turned on in parallel with the coil of an electromagnet, on a contactor operation it has been proposed by the authors to change the parameters of the base coil in such a way that an import power of a circuit of control could remain unchanged:
\[ \frac{U_{KB}^{2}}{R_{KB}} = \frac{U_{KB}^{2}}{R_{K} + R_{E}} = P_{KB} \quad (17) \]

where \( R_{KB} \), \( P_{KB} \) - the resistance of a coil and the power of control of a base contactor respectively;
\( R_E \) - changed resistance of a coil;
\( R_E \) - equivalent resistance of a circuit which by-passes a condenser.

\( R_E \) and \( R_{KB} \) are determined in the following way:
\[ R_E = \frac{U_K}{U_{KB}} \cdot R_{KB} = k \cdot R_{KB} \quad (18) \]

As \( R_{KB} = R_K + R_E \) then
\[ R_K = R_{KB} \cdot (1 - k) \quad (19) \]

The power on the changed coil:
\[ P_K = P_{KB} \cdot (1 - k) \quad (20) \]

In case of using a base contactor without changes the power in the coil would be \((1 - k)^2\) times lower than in the preceding case:
\[ P_y = P_{KB} \cdot (1 - k)^2 \quad (21) \]

So, the correlations obtained allow to calculate all the processes occurring in the circuit of electromagnetic drive and to choose the parameters of its main elements rationally.

V. THE RESULTS OF CALCULATING THE PARAMETERS OF THE ELEMENTS OF AN ELECTROMAGNETIC DRIVE CIRCUIT

The calculation values of the main parameters of the elements of an electromagnetic drive circuit, participating in the commutation process of a completely controlled power SK, are presented in table 1. The calculations have been carried out according to the formulae (18) – (20), (13) – (16), (4) – (7), (10), (11). The contactors of the series KTI6000 were used as a base contactor. The main parameters of a circuit of their electromagnetic drive are given in table 2 [12].

<table>
<thead>
<tr>
<th>( I_{\text{nom}} ) A</th>
<th>( U_{\text{nom}} ) V</th>
<th>( U_K ) V</th>
<th>( R_K ) Ohm</th>
<th>( R_E ) Ohm</th>
<th>( P_K ) W</th>
<th>( U_{KB} ) V</th>
<th>( U_{CTR} ) V</th>
<th>( C_k ) uF</th>
<th>( T_{\text{disch}} ) s</th>
<th>( t_1 ) s</th>
<th>( t_2 ) s</th>
<th>( t_{\text{charge}} ) s</th>
</tr>
</thead>
<tbody>
<tr>
<td>100, 160</td>
<td>before 1000 V</td>
<td>220</td>
<td>0.1</td>
<td>2562</td>
<td>284.47</td>
<td>15.3</td>
<td>22</td>
<td>9</td>
<td>394</td>
<td>0.1</td>
<td>0.053</td>
<td>0.24</td>
</tr>
<tr>
<td>250</td>
<td>1613.3</td>
<td>179.2</td>
<td>24.3</td>
<td>1089</td>
<td>1210</td>
<td>36</td>
<td>615.53</td>
<td>68.17</td>
<td>63.9</td>
<td>858.25</td>
<td>0.138</td>
<td>0.074</td>
</tr>
<tr>
<td>400</td>
<td>1617.5</td>
<td>179.2</td>
<td>24.3</td>
<td>1089</td>
<td>1210</td>
<td>36</td>
<td>615.53</td>
<td>68.17</td>
<td>63.9</td>
<td>858.25</td>
<td>0.138</td>
<td>0.074</td>
</tr>
<tr>
<td>630</td>
<td>1617.5</td>
<td>179.2</td>
<td>24.3</td>
<td>1089</td>
<td>1210</td>
<td>36</td>
<td>615.53</td>
<td>68.17</td>
<td>63.9</td>
<td>858.25</td>
<td>0.138</td>
<td>0.074</td>
</tr>
</tbody>
</table>

The analysis of the calculation results shows that calculation parameters of the elements of an electromagnetic drive circuit provide reliable operation of the circuit of controlling the commutation of the completely controlled
SK in the whole range of nominal currents contactors using the contactless method. At each of the proposed nominal currents of a base contactor the charging time of a condenser $C_1$ up to the voltage $U_{CT}$ in case of its turning on is lower than the minimum time of turning on a contactor and the time of discharge in case of turning off is always higher than the maximum time of cutting off a contactor. However, the dimensions and cost of a condenser $C_1$ despite its rather high capacity, will be inconsiderable, as we use an electrolytic condenser with low voltage (not higher than 25 V).

Calculation methods as well as calculation parameters of a current transformer and the circuit of controlling the commutation of a completely controlled SK for the range of nominal currents (100 – 130 A) is presented in the work [5].

Calculation methods of overload capacity of a completely controlled SK as well as overlading limiter are presented in [13], where it is shown that power semiconductor devices performing the role of SK in hybrid contactors can be applied without coolers using natural cooling. Providing of allowable level of overloading lower than $2.5 \cdot U_{NOM}$ can be achieved due to the turned on series-parallel low power varistors with the corresponding mass and cost.

VI. EXPERIMENTAL RESEARCH OF ELECTROMAGNETIC DRIVE OF THE PROPOSED CONTACTORS

The aim of the research is to determine such important for the analysis of the work of an electromagnetic drive parameters as the value of a contactor turning on time $t_{\text{turn-on}}$, a condenser charging time $C_{1}$, $t_{\text{charge}}$ at turning on a contactor and the time of its discharging $t_{\text{disch}}$ at turning off. The researches have been carried out using a special installation, the electrical circuit of which is shown in figure 3.

The originality of the experiment is that in the course of the research a base contactor KTIP6000 with the nominal current 250 V without any changes has been used.

Furthermore, operating conditions of electromagnetic drive of this contactor were the same as in the research, given in sections 4 and 5 for the same contactor. It has been achieved due to the following conditions:

\[
\frac{u_{KB}}{R_{KB}} = \frac{u_{KB}}{R_{KB} + R_{E}} = P_{KB};
\]

\[
U_{se} = \gamma \cdot U_{KB};
\]

\[
k = \frac{R_{E}}{R_{KB} + R_{E}} = 0.1;
\]

\[
P_{K} = P_{KB} \cdot 0.9; \quad \frac{U_{VT}}{R_{E}} = \frac{U_{CTE}}{R_{E}}.
\]

Where $U_{KB} = 220$ V; $P_{KB} = 27$ W

\[
P_{K} = 24.3$ W;
\]

\[
\gamma = \frac{1}{U_{KB}} \cdot \sqrt{P_{KB} \cdot (R_{KB} + R_{E})} = 1.054;
\]

\[
U_{se} = 231.92$ V; $R_{E} = 199.2$ Ohm;
\]

\[
U_{VT} = 10$ V - corrected values of controlling voltage, equivalent to the resistance, the voltage of the voltage regulator stabilization $VD5$ respectively.

In this case the value a condenser capacity remained unchanged and equal to 858 uF.

Time measuring was carried out with the help of dual-pattern digiscope, and the terminals 1 and 2 were used for measuring $t_{\text{turn-on}}$, and the terminals 1 and 4 – for measuring $t_{\text{disch}}$ and $t_{\text{charge}}$. Measuring of $t_{\text{turn-on}}$ for the base contactor was carried out when $U_{K} = 250$ V and closed contacts $K1$.

The voltage measuring was carried out with the help of a digital voltmeter. The results of comparison of experimental and calculation values of the parameters research are presented in table 3. Furthermore, calculations were carried out according to the same methods as in section 5.

Fig. 3. Electrical circuit of the acting installation
TABLE III  EXPERIMENTAL AND CALCULATION VALUES OF THE MAIN PARAMETERS OF AN ELECTROMAGNETIC DRIVE.

<table>
<thead>
<tr>
<th>( I_{\text{Nom}} ) A</th>
<th>( R_{\text{K}} ) Ohm</th>
<th>( R_{\text{e}} ) Ohm</th>
<th>( U_{\text{CTR}} ) V</th>
<th>( U_{\text{OK}} ) V</th>
<th>( \delta )</th>
<th>( t_{\text{turn-off S}} ) ns</th>
<th>( g_c )</th>
<th>( t_{\text{charge S}} ) ns</th>
<th>( \delta )</th>
<th>( t_{\text{disch S}} ) ns</th>
<th>( \delta )</th>
</tr>
</thead>
<tbody>
<tr>
<td>250</td>
<td>1993</td>
<td>198.2</td>
<td>10</td>
<td>23.5</td>
<td>+4.1</td>
<td>0.201</td>
<td>+2.2</td>
<td>0.201</td>
<td>+5.98</td>
<td>0.336</td>
<td>-6.1</td>
</tr>
<tr>
<td>300</td>
<td>1993</td>
<td>198.2</td>
<td>10</td>
<td>23.5</td>
<td>+4.1</td>
<td>0.201</td>
<td>+2.2</td>
<td>0.201</td>
<td>+5.98</td>
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<td>350</td>
<td>1993</td>
<td>198.2</td>
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<td>0.201</td>
<td>+5.98</td>
<td>0.336</td>
<td>-6.1</td>
</tr>
</tbody>
</table>

The analysis of the results given in table 3 showed a high level of coincidence of experimental and calculation values of the investigated parameters. The maximum error does not exceed 6.1% and it is quite acceptable for the engineering calculation methods. These researches also showed that it is not efficient to increase the value \( k \) higher than 0.1 because of possible failure of a drive operation.

VII. THE DISCUSSION OF THE RESEARCH RESULTS

The application of the hybrid contactors of an electronic circuit control by an electromagnetic drive current, presented in the schemes, allows to create a series of positive characteristics, increasing their competitiveness. It can be achieved by the introduction, in parallel with a drive coil, of a special electronic circuit of turn-on of a completely controlled power SK, containing a condenser, setting the time and a controlled transistor key, in an output circuit of which a low-power optron thyristor is turned on. In parallel with the mentioned condenser an auxiliary transistor key is connected, providing a discharge in case of commutation current flow from the main contactors circuit to SK circuit with the help of an additionally introduced auxiliary transformer coil. This circuit provides a reliable contactless commutation of a power SK in all operating conditions of a contactor. Additional positive characteristics, obtained as a result of using technical solutions, proposed by the authors, are clearly defined in section 3 and were confirmed with the results given above the theoretical and experimental researches.

The weak point of these contactors is the fact that the introduction of a charged condenser in parallel with a drive coil decreases the control power of this coil and consequently, complicates the process of connecting a contactor. As a result, to minimize this influence it is proposed to limit the voltage value on this condenser at the level 0.1-\( U_{K} \).

With the existing base of elements, the above mentioned complicates the application of this contactor when the voltage level of control is lower than 110 V. But this weak point is compensated with the achieved positive characteristics.

Carried out research of nonstationary processes, occurring in the contactors circuits in case of commutation, allowed to develop the methods of calculating the main elements of an electronic circuit of a contactor, suitable for engineering calculations.

Furthermore, it has been shown that the charging time of a condenser, setting the time up to the level of voltage providing the turn-on of a low-power optron thyristor when a contactor is turned on, shouldn’t be higher than the value of the minimum time of its turn-on, and the discharge time of this condenser when turning off shouldn’t be lower than the maximum time of turning off a contactor.

It has been also shown that the consumption capacity in controlling circuits of the proposed contactor should be equal to the same capacity of a base contactor.

The results of calculations and experimental researches, presented in the article as well as in the works published by the authors before, show real possibility of creating hybrid contactors of direct current with the proposed principle of operation, rated for currents 100 630 A and voltage up to 1000 V.

The results obtained may be applied when developing contactors, which can be efficiently used in hard maintenance conditions with frequent engine starts, for example, in electric transport, in crane equipment, in rolling production of metallurgical plants etc, as well as in electrical systems of alternative electric power industry in conditions of increased explosion and fire safety requirements. Furthermore, their positive characteristics, mentioned above, considerably increase their competitiveness.

VIII. CONCLUSIONS

It has been substantiated that the proposed hybrid contactors as compared with the existing ones have the following advantages:

Increased reliability of operation provided by excluding of unreliable contact circuit on the basis of current relay from the power SK control circuit and the possibility of emergency restart of a power SK when disconnecting the contactor is completely excluded;

Economical operating conditions of the elements of a contactor electronic circuit;

The influence of a net voltage on the elements of a control circuit is excluded;

The dimensions, mass and cost are reduced due to essential simplification of a control circuit (time relay and a large non-process current relay are excluded, the connections between the elements are simplified);

The parameters and operating conditions of an electronic control circuit do not depend on a net voltage and are determined only by the current which is turned off and it allows to apply the proposed technical solutions also for creating hybrid contactors for the voltage higher than 1000 V.

The lack of a commutation zone with an arc increases its commutation wear resistance as well as allows to use it in conditions of explosion and fire safety requirements.

It has been stated that for providing reliable commutation of a circuit it is necessary that the time of a condenser charging, setting the time up to the level of voltage and providing turn-on of a low-power optron thyristor in case of turning on a contactor, shouldn’t be above the value of minimum time of its turn-on and the discharge time of this condenser in case of turn-off, shouldn’t be below the maximum time of turning off a contactor.

The developed methods of calculating the main elements of a contactor electronic circuit allows to make calculations with sufficient accuracy for engineering calculations and it is confirmed with the results of experimental researches. The research results show the real possibility of creating competitive hybrid contactors of direct current with the
Принципи та методи розрахунку гібридних контакторів постійного струму, що керуються струмом електроприводу

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Показано, що принцип керування струмом електромагнітного приводу гібридного контактора постійного струму реалізовано шляхом введення послідовно з котушкою приводу спеціально електричної схеми керування включення силового НК, що містить конденсатор, що задає час, та керований малопотужний транзисторній ключ, в вихідне коло якого ввімкнений провідниковий ключ, який забезпечує за допомогою додатково введеного вторинного обмотки трансформатора струму його розряд при переїжджанні комутаційного струму з коль холодних контактів в коль силового напівпровідникового ключа.

Визначені особливості процесів заряду та розряду конденсатора, що задає час, в різних режимах роботи контактора. При цьому було встановлено, що для забезпечення надійності комутації кота необхідно, щоб час заряду конденсатора, що задає час, до рівня напруги, що забезпечує включення малопотужного оптронного транзистора, при чому паралельно вказаному конденсатору вмикається допоміжний транзисторній ключ, який забезпечує за допомогою додатково введеного вторинної обмотки трансформатора струму його розряд при переїжджанні комутаційного струму з коль холодних контактів в коль силового напівпровідникового ключа.

В результаті проведених досліджень також було показано, що пропоновані гібридні контактори завдають введення керування струмом електромагнітного приводу та введення нових зв'язків порівняно з існуючими мають властивості, що підвищують їх конкурентоспроможність. Зокрема в них підвищена надійність роботи, зменшені габарити та вартість, покращені їх виробничо-технологічні показники, розширена область застосування.

Прискладом використання одержаного наукового результату є можливість створення конкурентоспроможних нових гібридних контакторів постійного струму на струми 100–630 А та напругу до 1000 В, що працюють у важких умовах експлуатації.

**Ключові слої – гібридний контакт, постійний струм, головні контакти, силовий напівпровідниковий ключ, керування струмом, електромагнітний привод.**

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